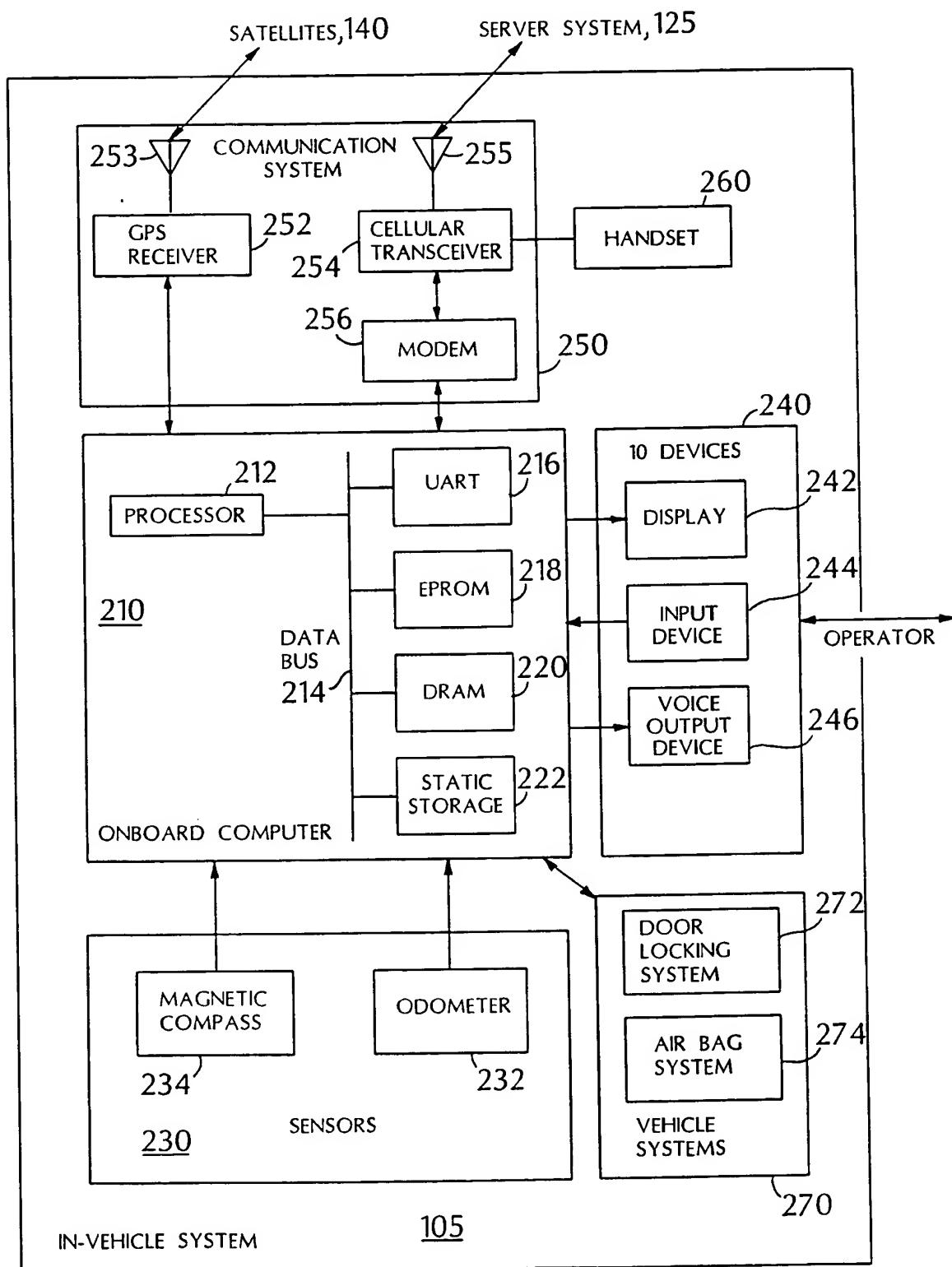


FIG. 1



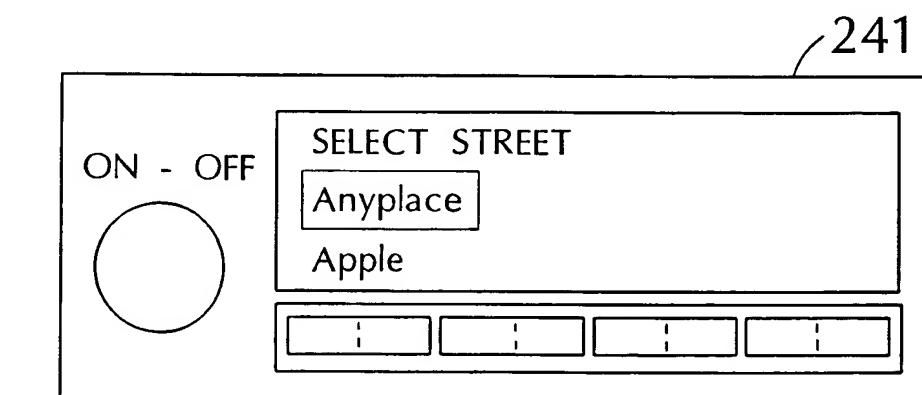
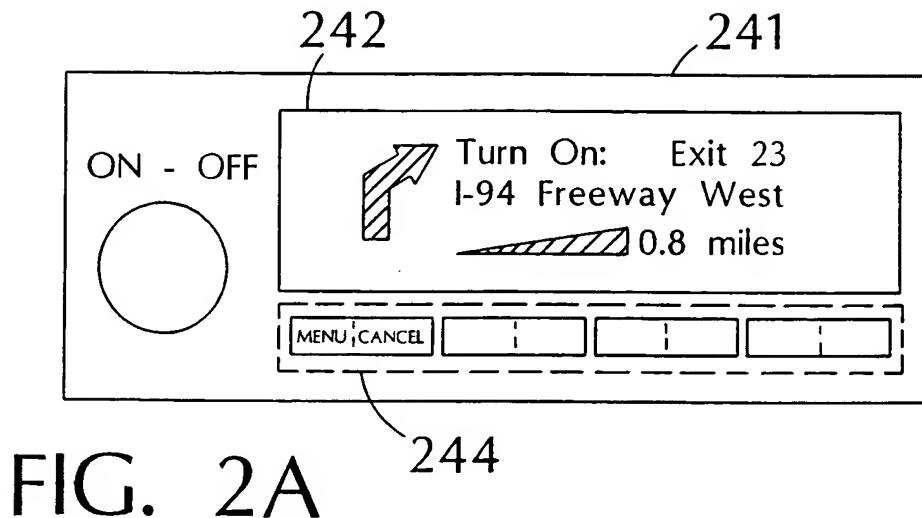


FIG. 2B

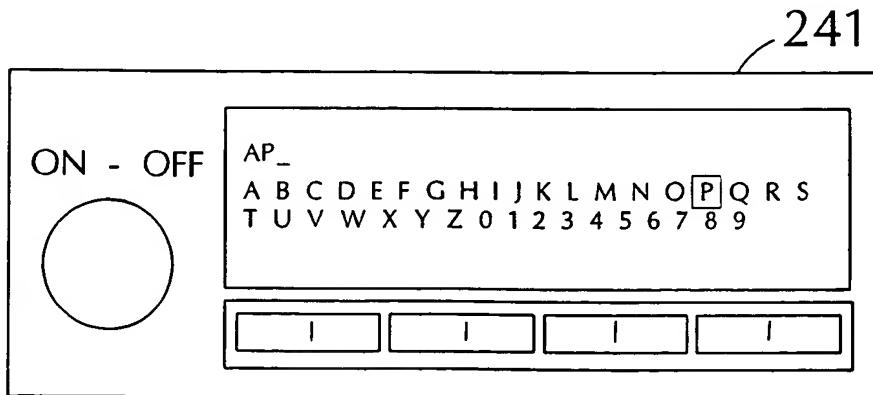


FIG. 2C

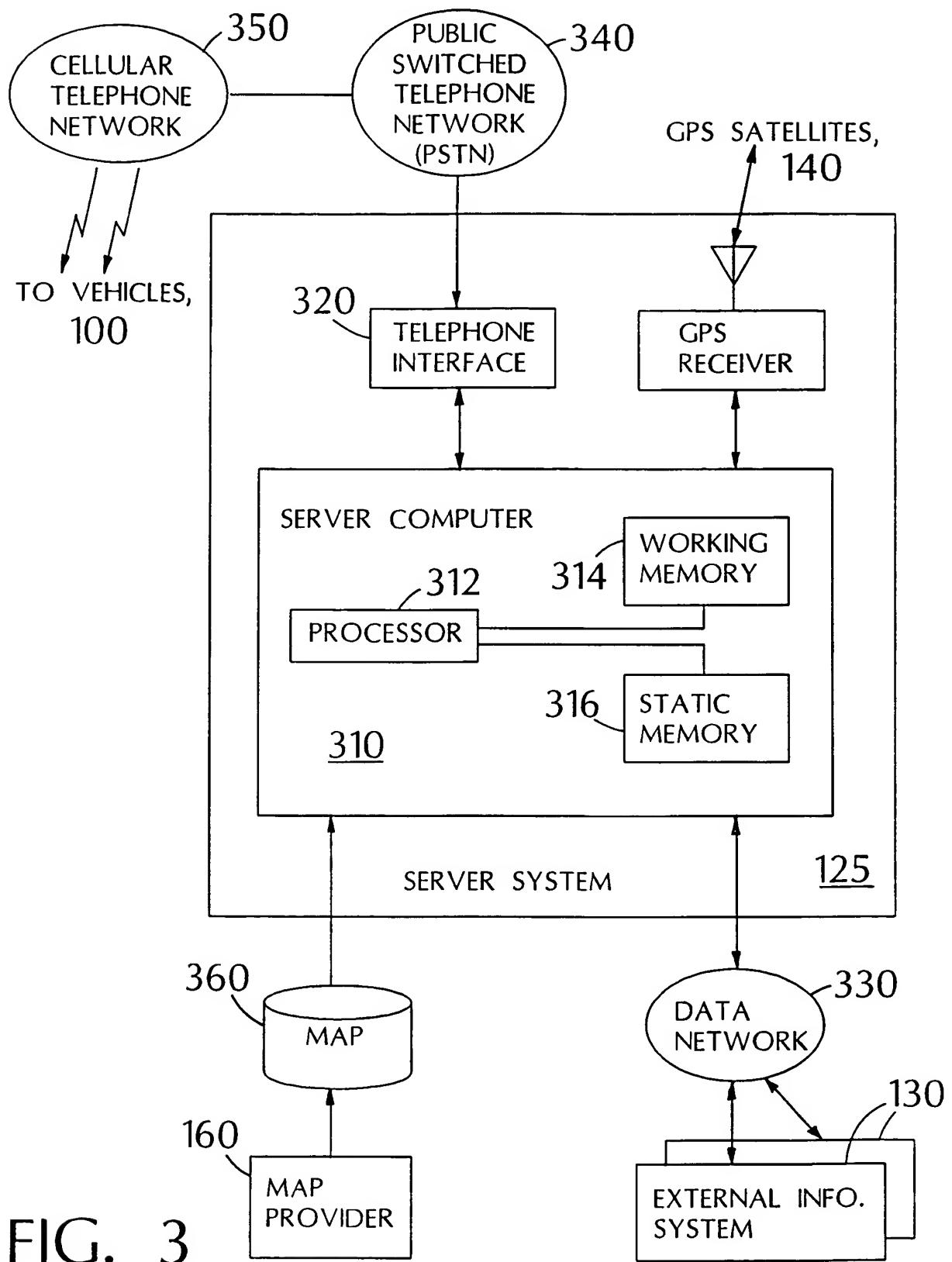


FIG. 3

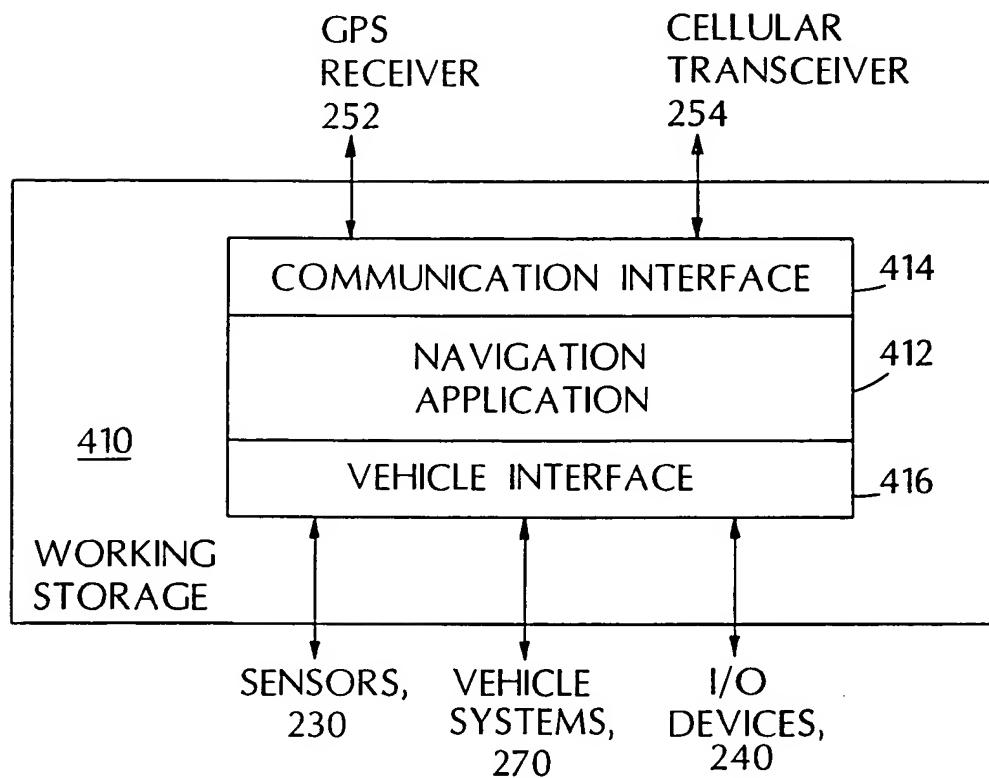


FIG. 4A

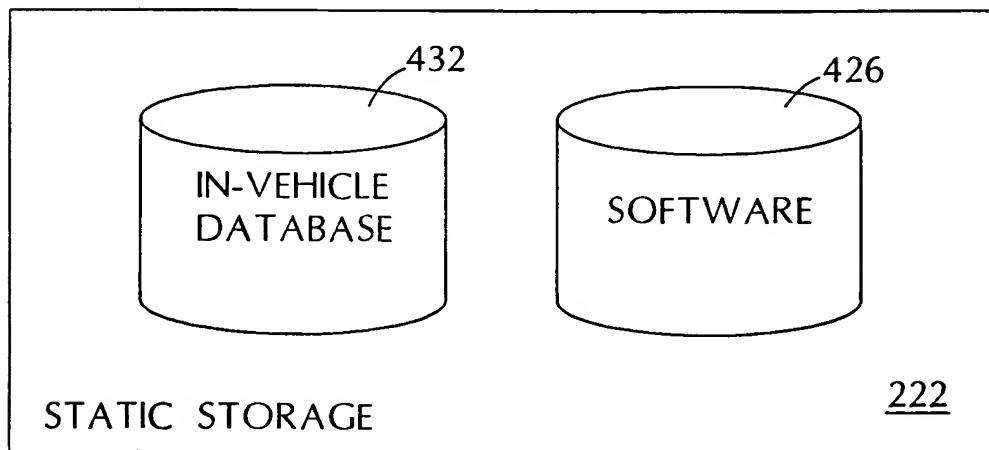


FIG. 4B

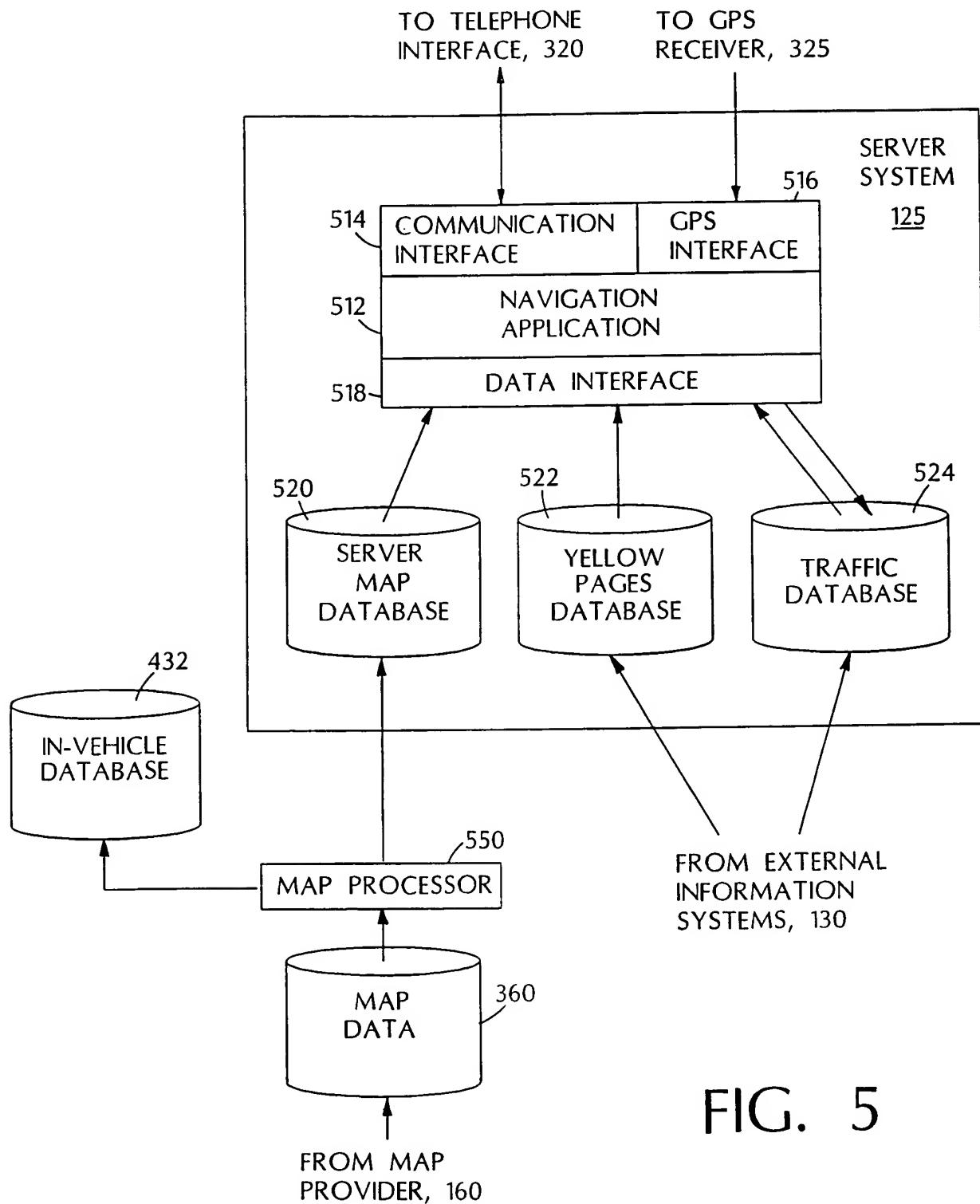
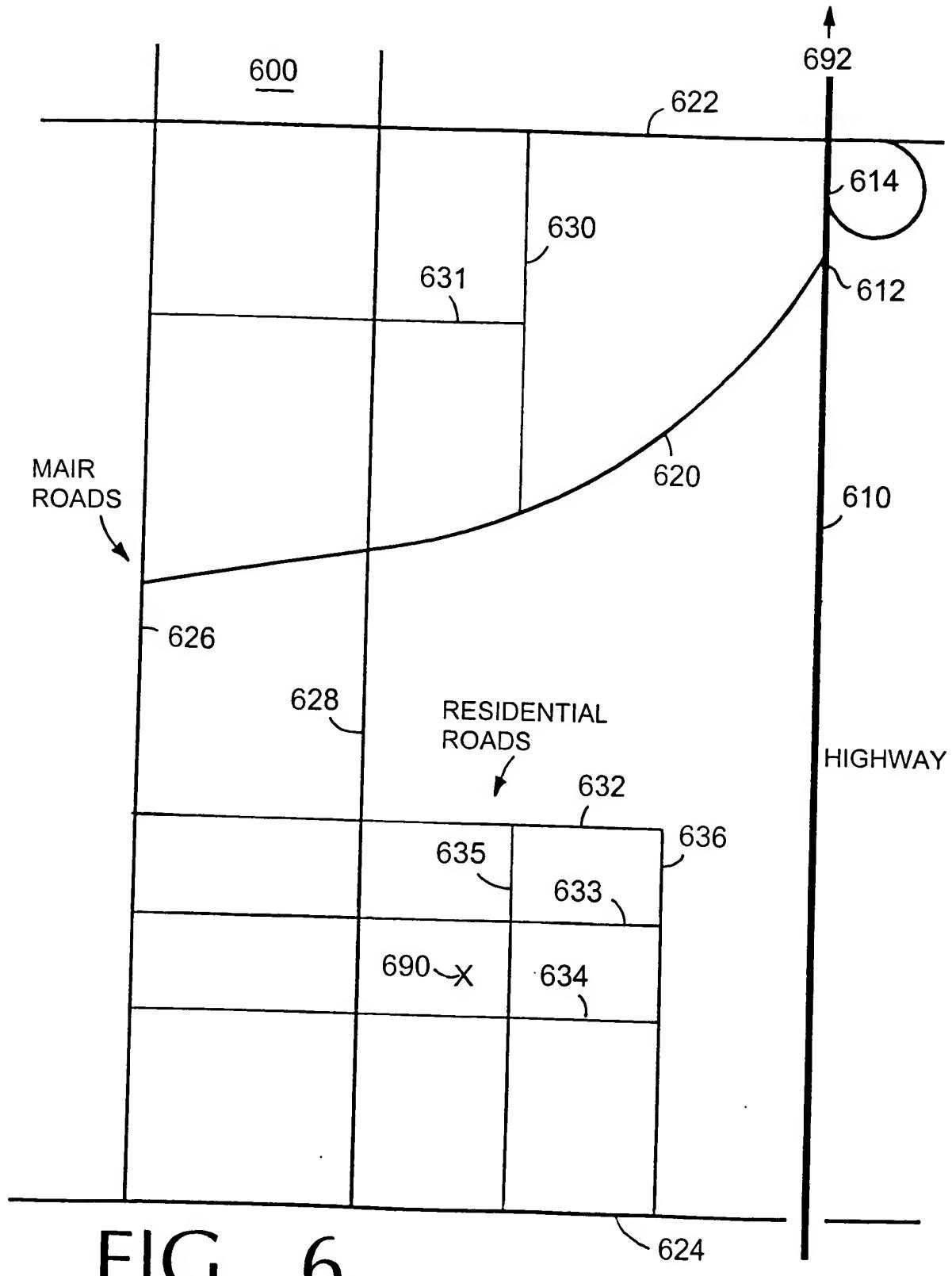


FIG. 5



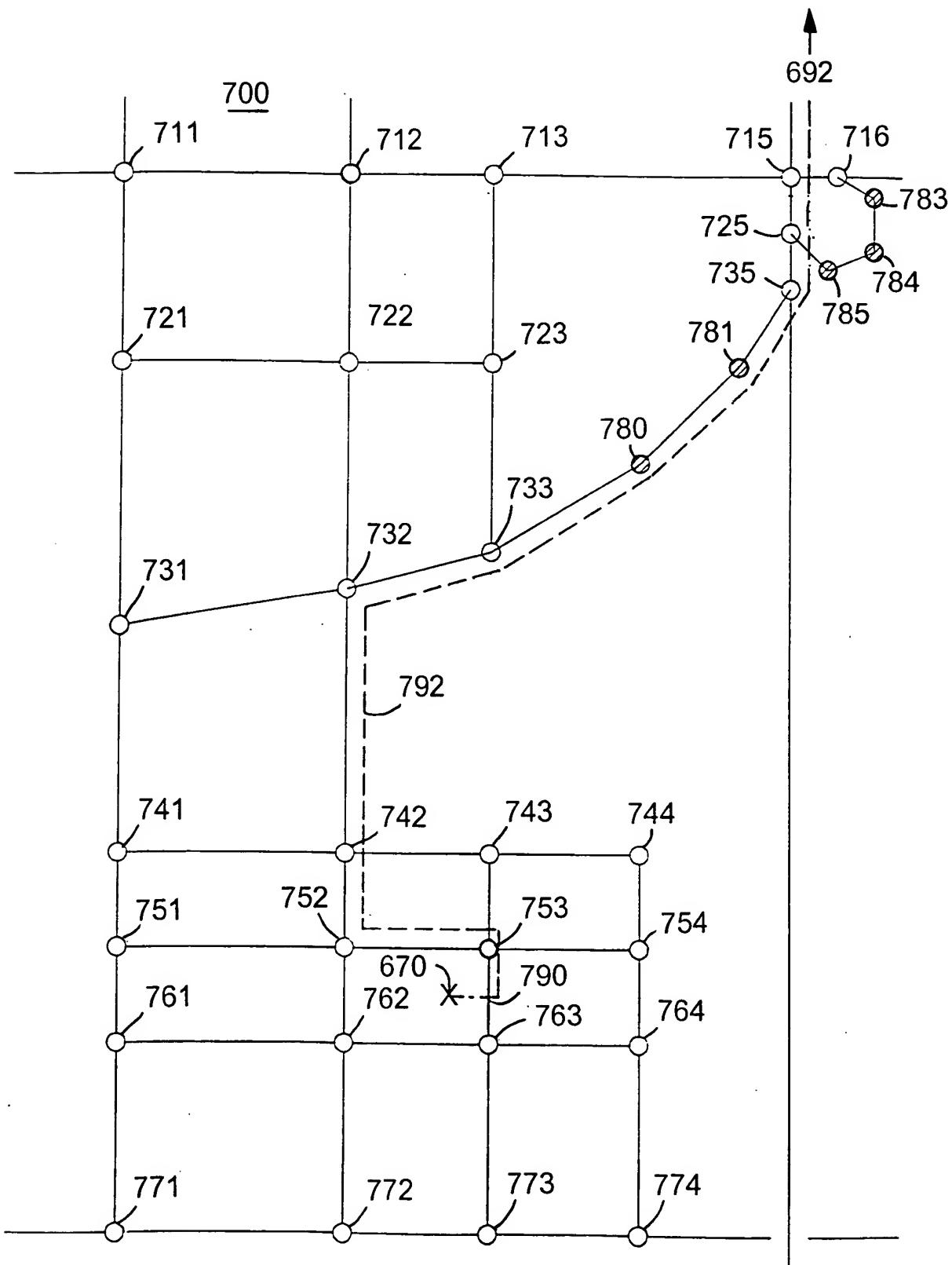


FIG. 7

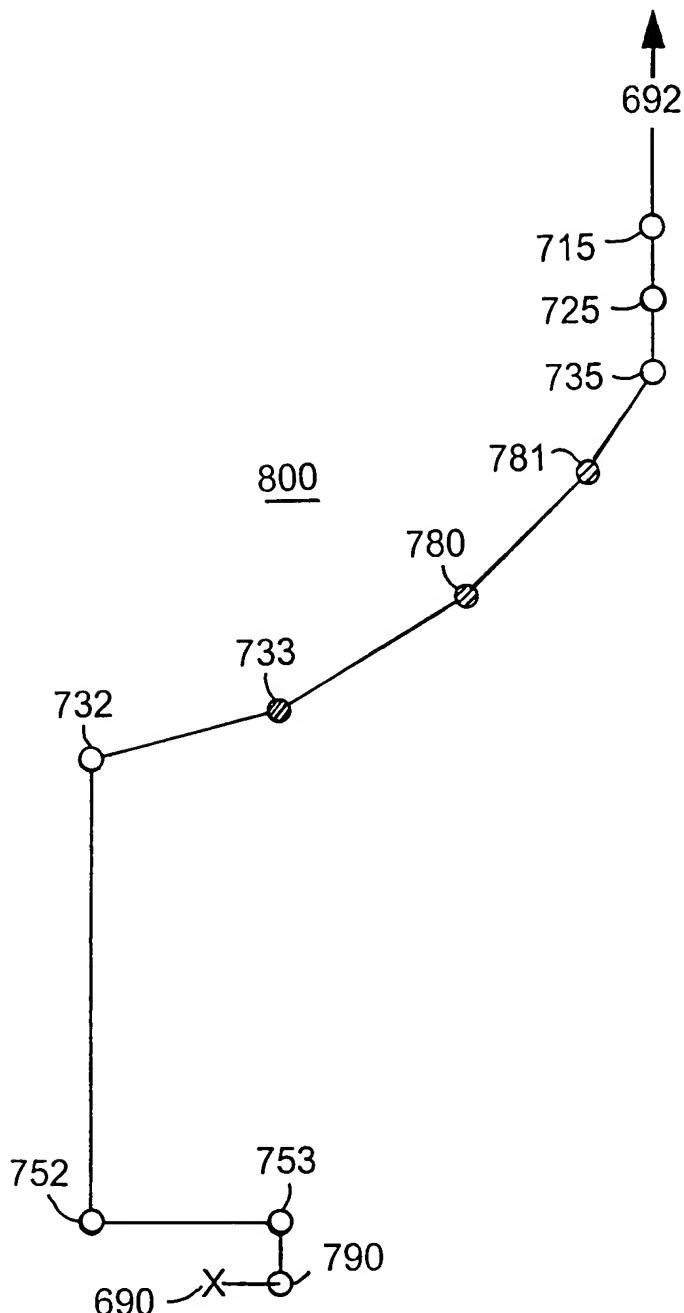
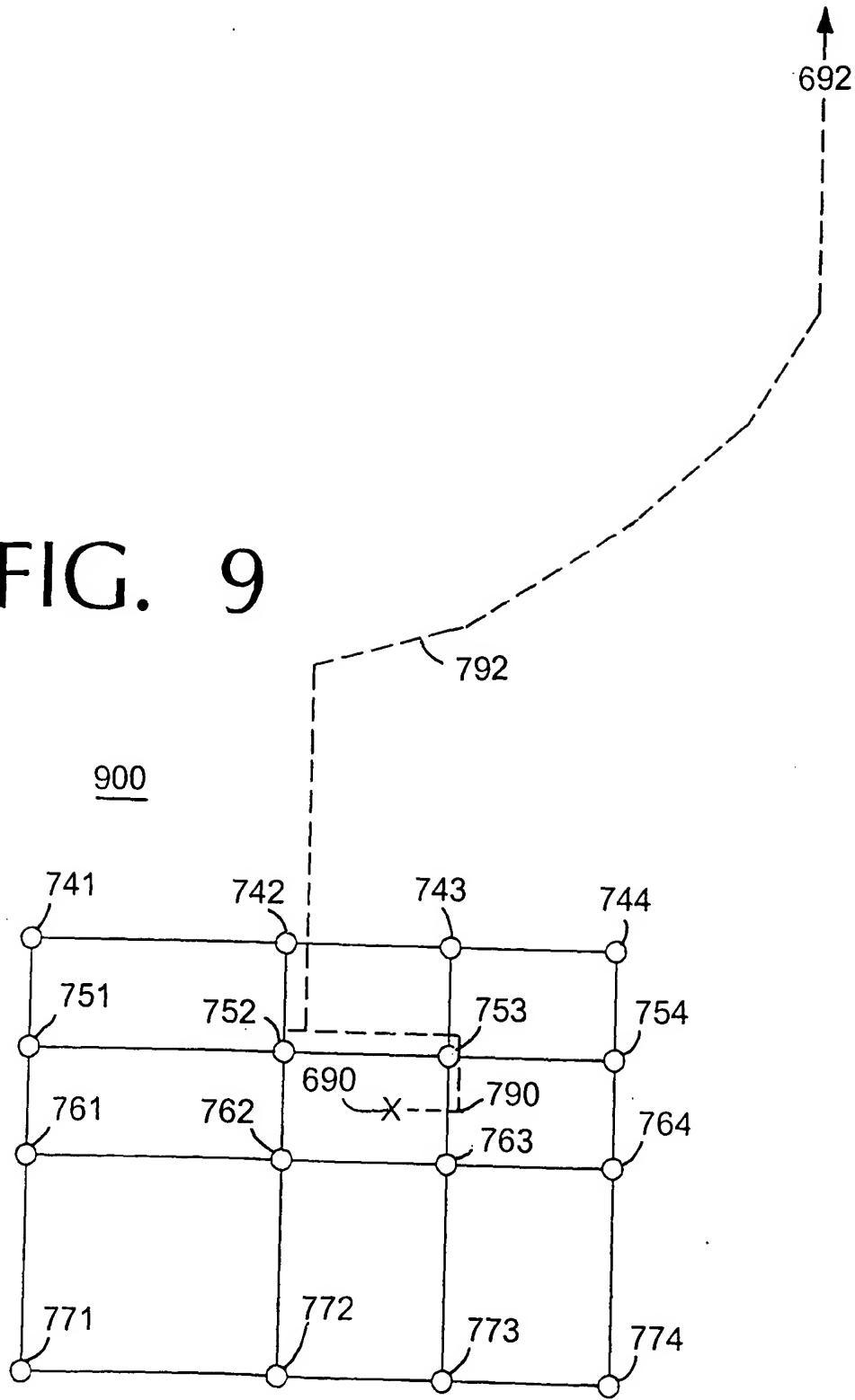


FIG 8

FIG. 9



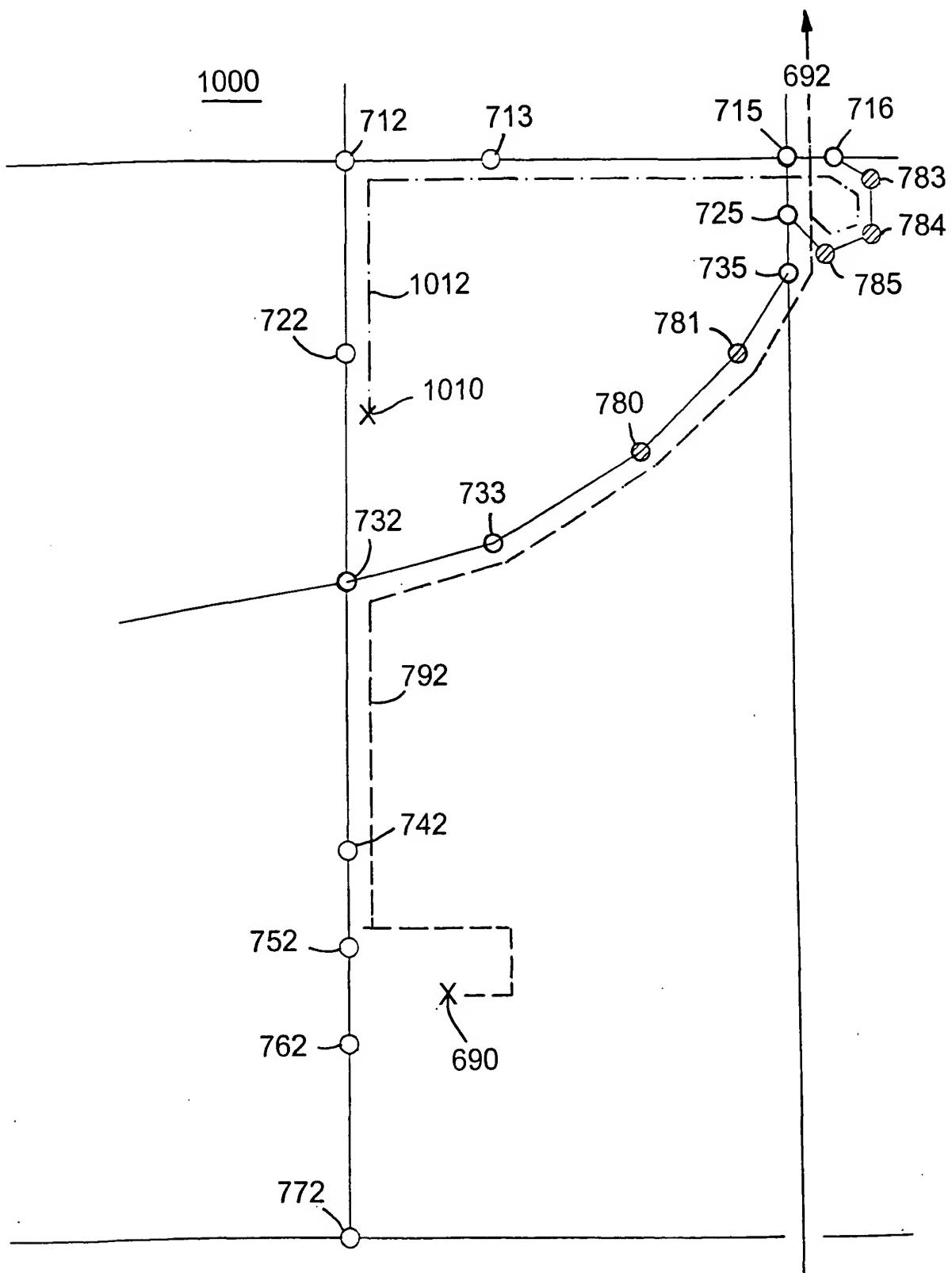


FIG. 10

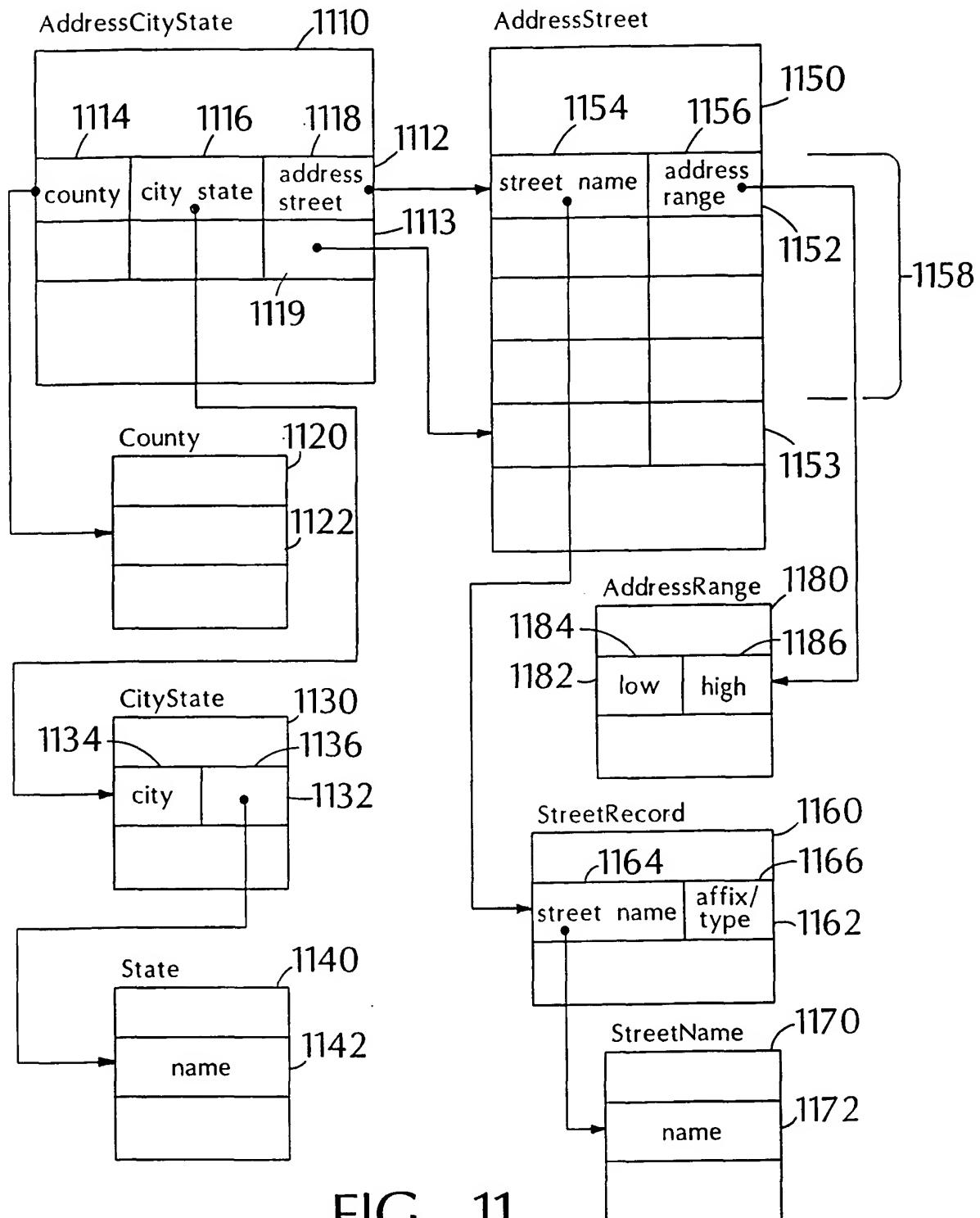


FIG. 11

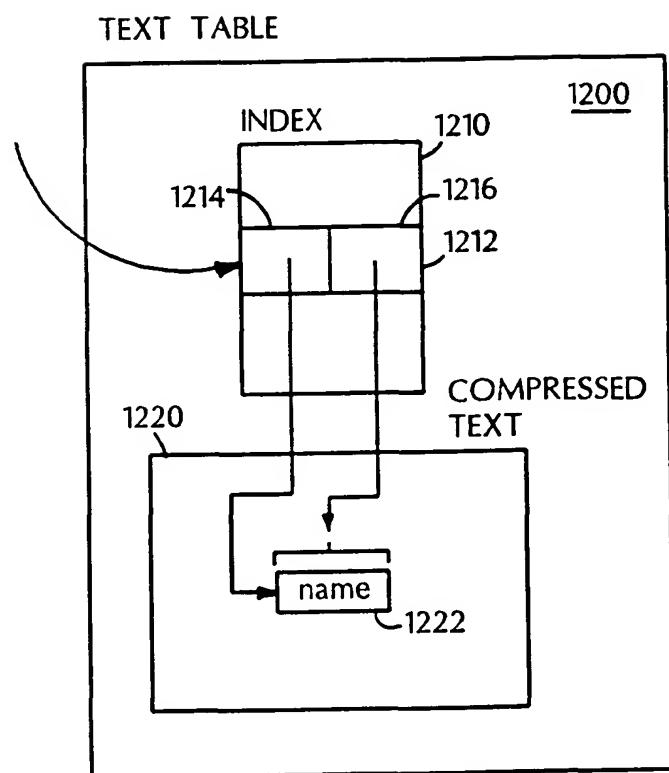


FIG. 12

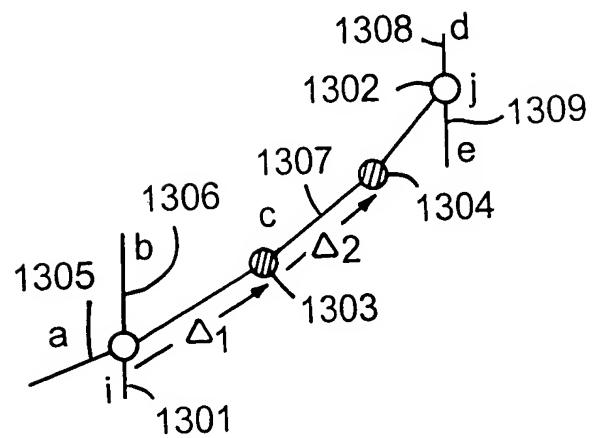
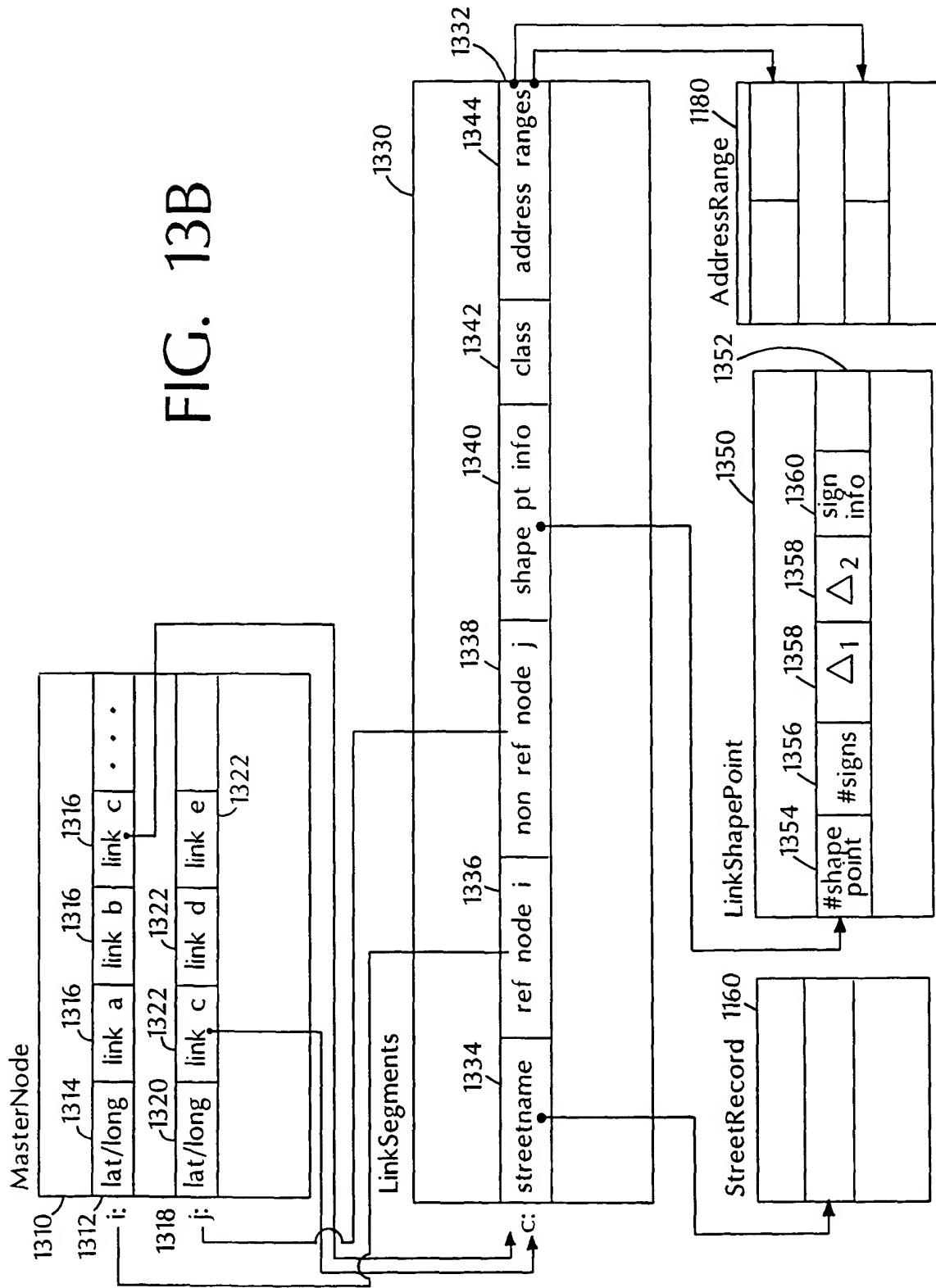
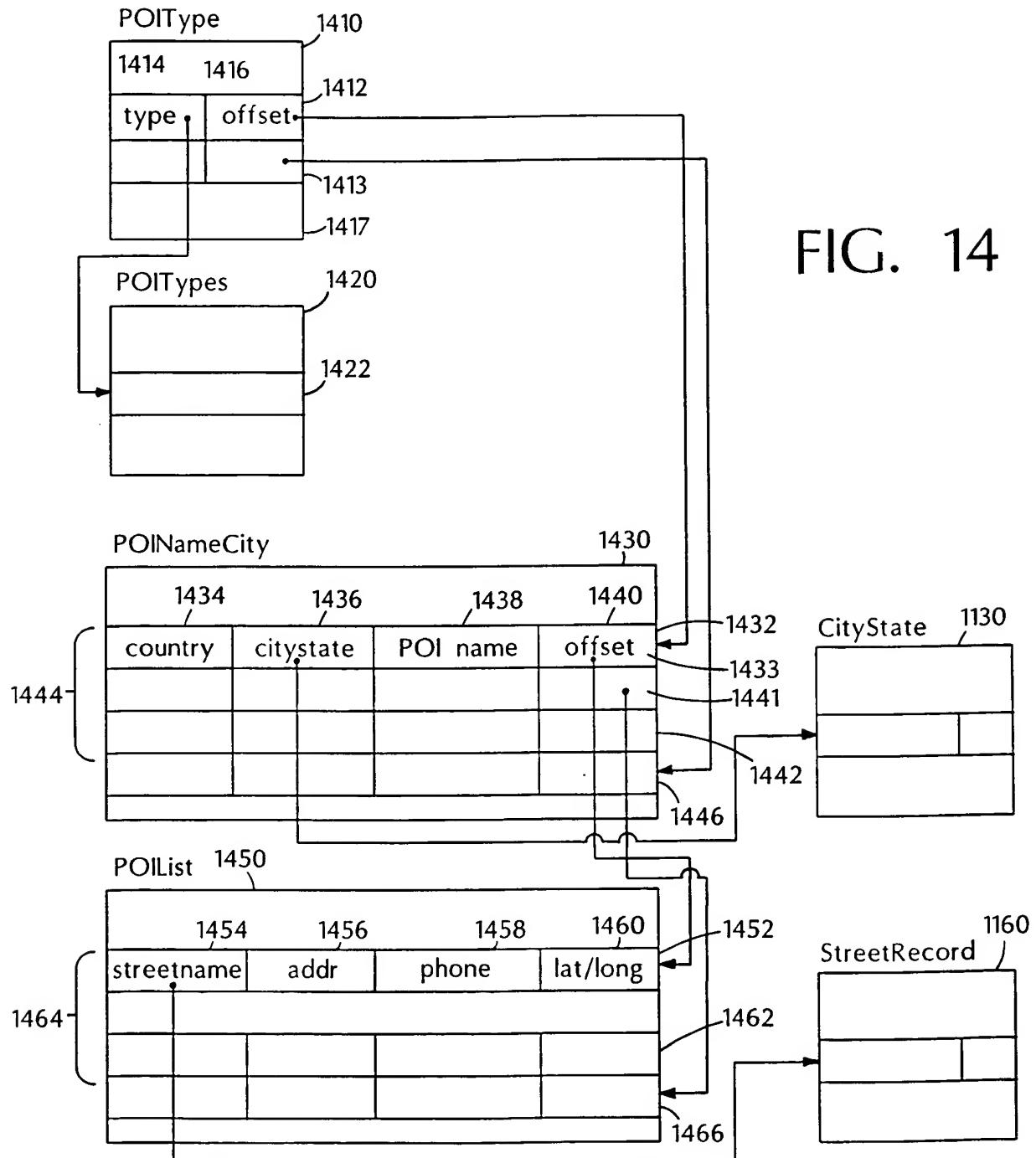


FIG. 13A

FIG. 13B





1501 **Plan Route (In-Vehicle):**

1502 Accept Destination Specification from Operator

1503 Determine Current Location Data

1504 Establish Communication Session with Server

1505 Send Destination Specification and Current Location Data to Server

1506 IF Destination Specification Requires Server Interaction THEN

1507 Accept Secondary Destination Specification Data from Server

1508 Accept Secondary Destination Specification from Operator

1509 Send Secondary Destination Specification to Server

1510 END IF

1511 Wait for Server Response

1512 Receive Planned Route, Spot Map, and Differential GPS Data from Server

1513 Close Communication Session with Server

FIG. 15A

1551 Plan Route (Server):

1552 Accept Communication Session with Vehicle

1553 Receive Destination Specification and Current Location Data from Vehicle

1554 Determine DGPS Correction Data

1555 Determine Vehicle Location

1556 IF Destination Specification Requires Further Operator Input THEN

1557 Determine Secondary Destination Specification Data

1558 Send Secondary Destination Specification Data to Vehicle

1559 Receive Secondary Destination Specification from Vehicle

1560 END IF

1561 Determine Planned Route to Specified Destination

1562 Determine Spot Map near Vehicle Location

1563 Send Planned Route, Spot Map, and DGPS Data to Vehicle

1564 Close Communication Session with Vehicle

FIG. 15B

```
1601    Startup Maneuvers:  
1602        Initialize Estimated Location using Differential GPS Data  
1603        WHILE Estimated Location is not at a Point of the Planned Route DO  
1604            Track Estimated Location using (D)GPS Data  
1605            Display Spot Map and Estimated Location on Display  
1606        END WHILE
```

FIG. 16

FIG. 18

1701 **Follow Route:**
1702 FOR Each Link on Planned Route DO
1703 At Initial Maneuver Initialize Off-Route Tolerance
1704 WHILE Vehicle Is Travelling to the Next Maneuver Point DO
1705 Increase Off-Route Tolerance
1706 Track Dead-Reckoning Location
1707 Track (D)GPS Location
1708 IF (Dead-Reckoning Location is more than Off-Route Tolerance
1709 from (D)GPS Location THEN
1710 GOTO Replan Route
1711 END IF
1712 IF Dead-Reckoning Location is within Maneuver
1713 Notification Window THEN
1714 Notify Operator of Next Maneuver
1715 END IF
1716 IF Dead-Reckoning Location is within Maneuver
1717 Detection Window THEN
1718 IF Next Maneuver is Detected THEN
1719 Update Dead-Reckoning Location
1720 Update DGPS Data
1721 END IF
1722 END IF
1723 UNTIL Maneuver was Detected OR
1724 Vehicle Leaves Maneuver Detection Window
1725 UNTIL Destination is Reached

FIG. 17

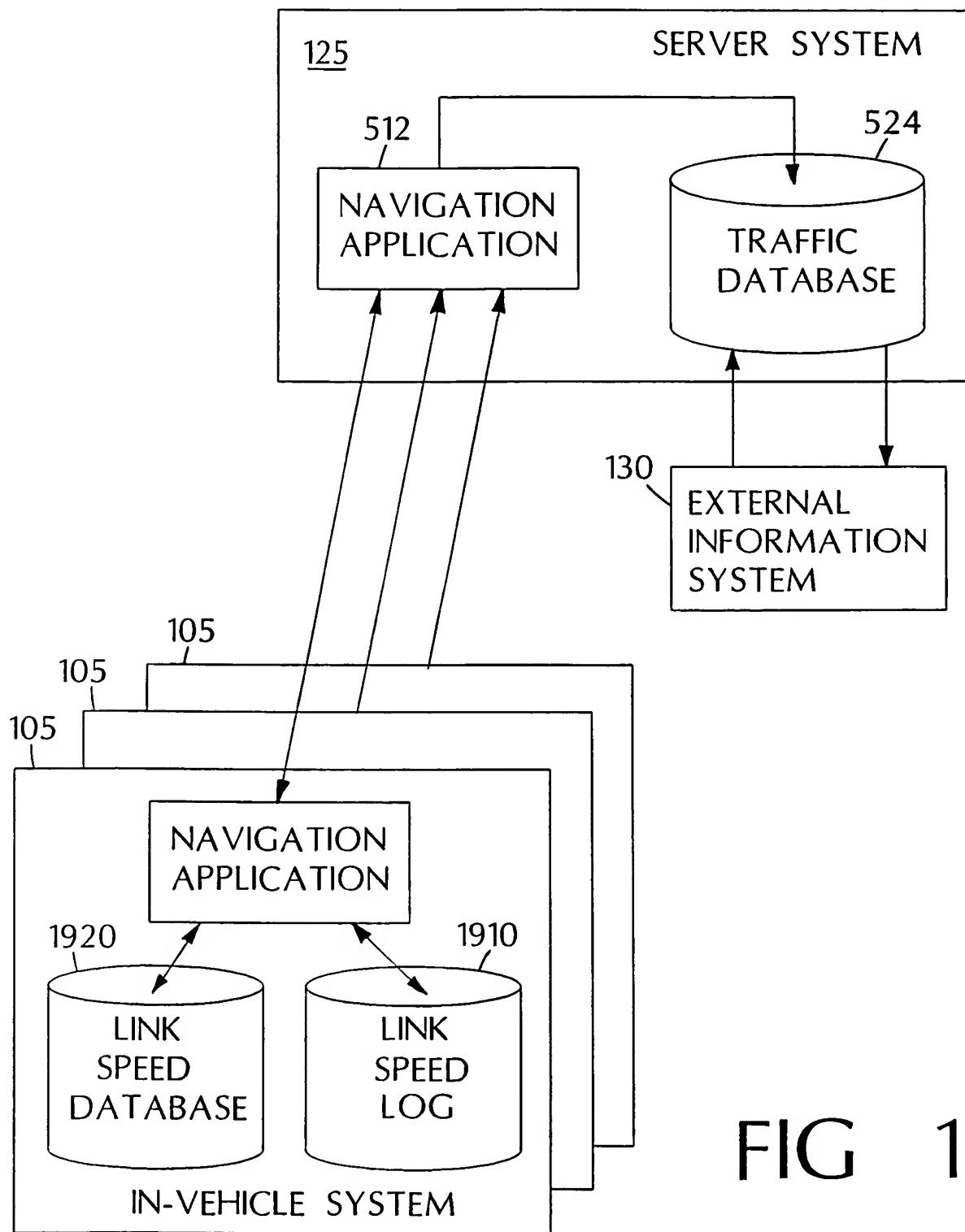


FIG 19

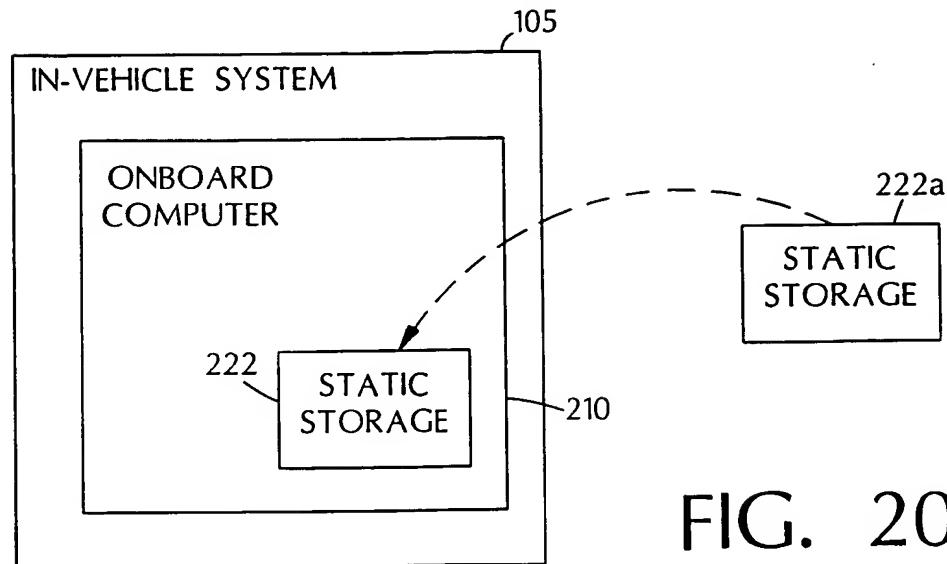


FIG. 20A

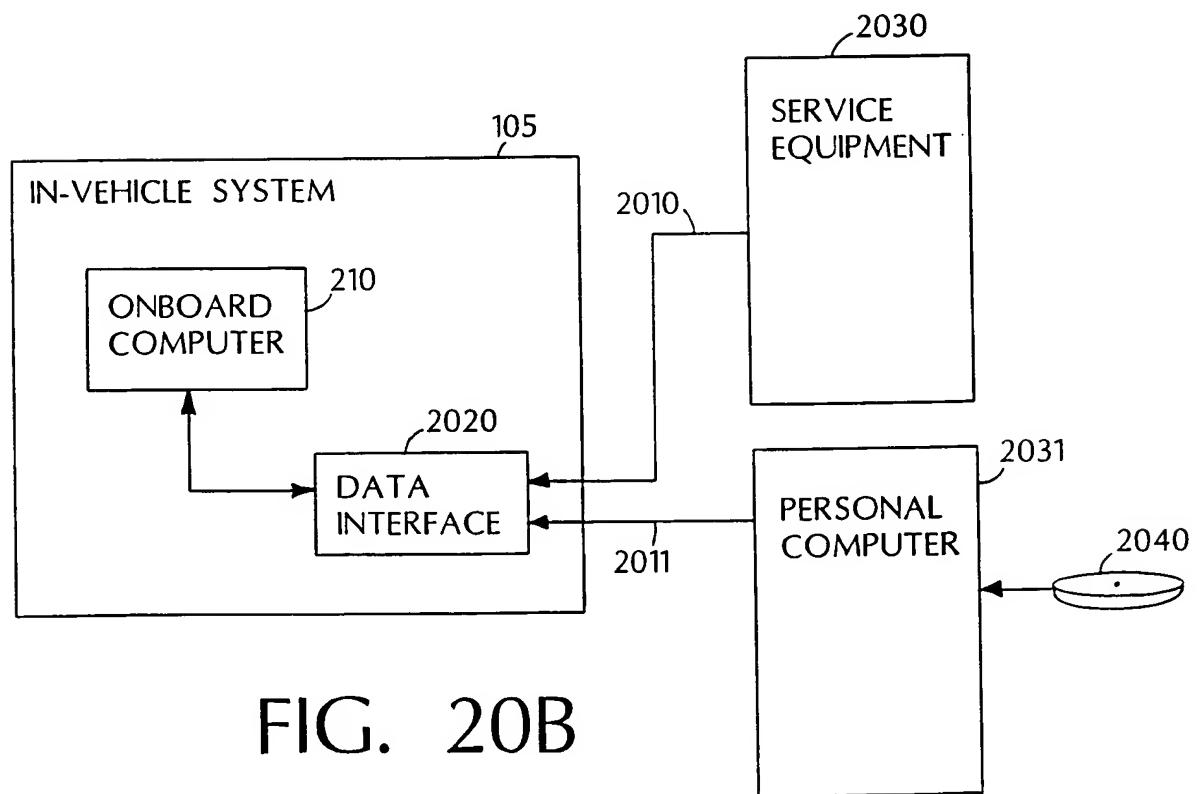


FIG. 20B

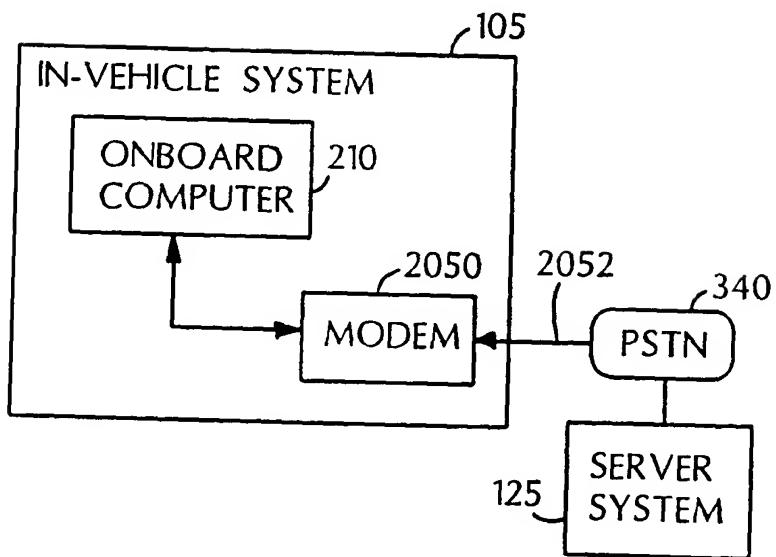


FIG. 20C

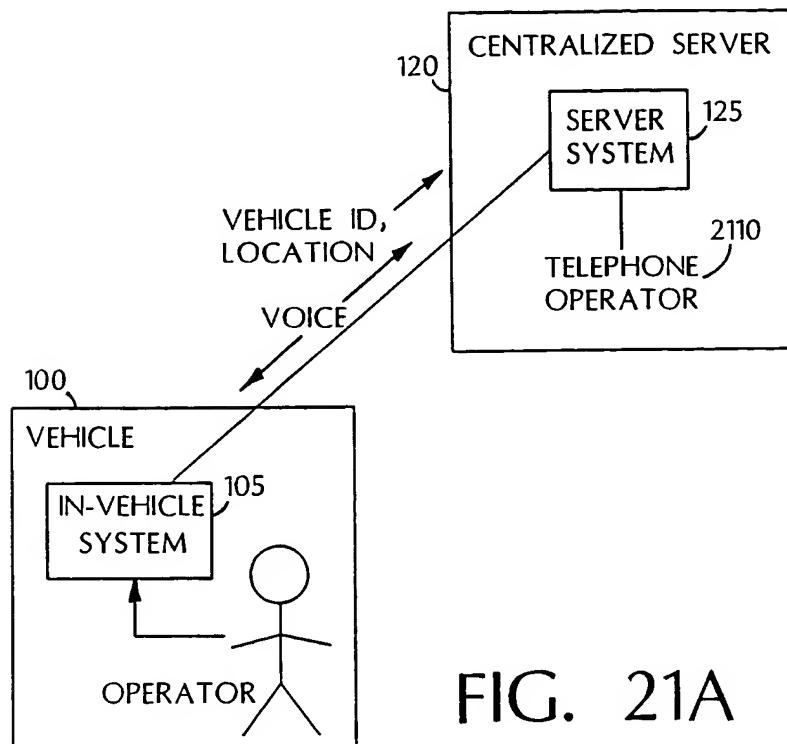


FIG. 21A

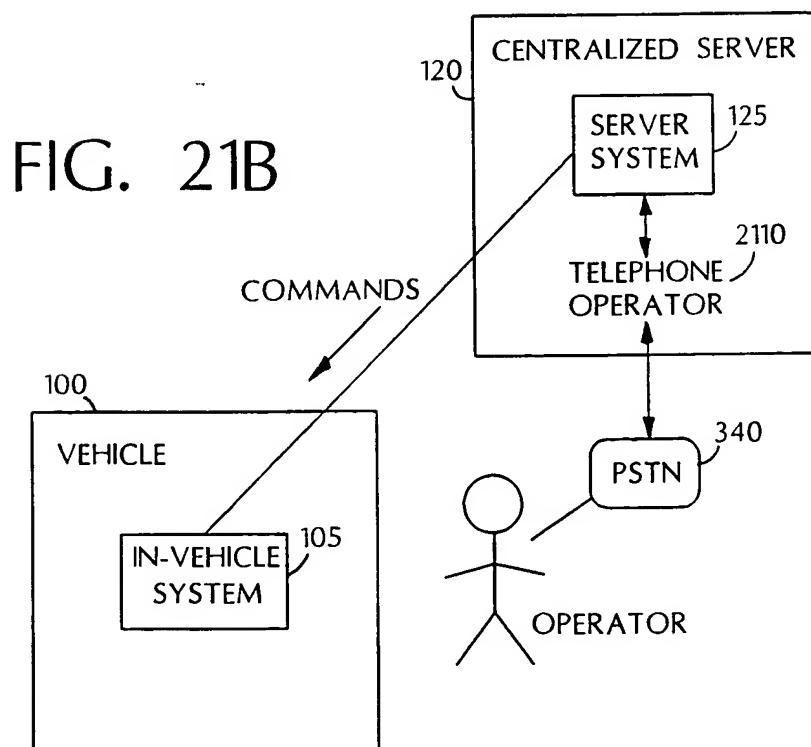


FIG. 21B

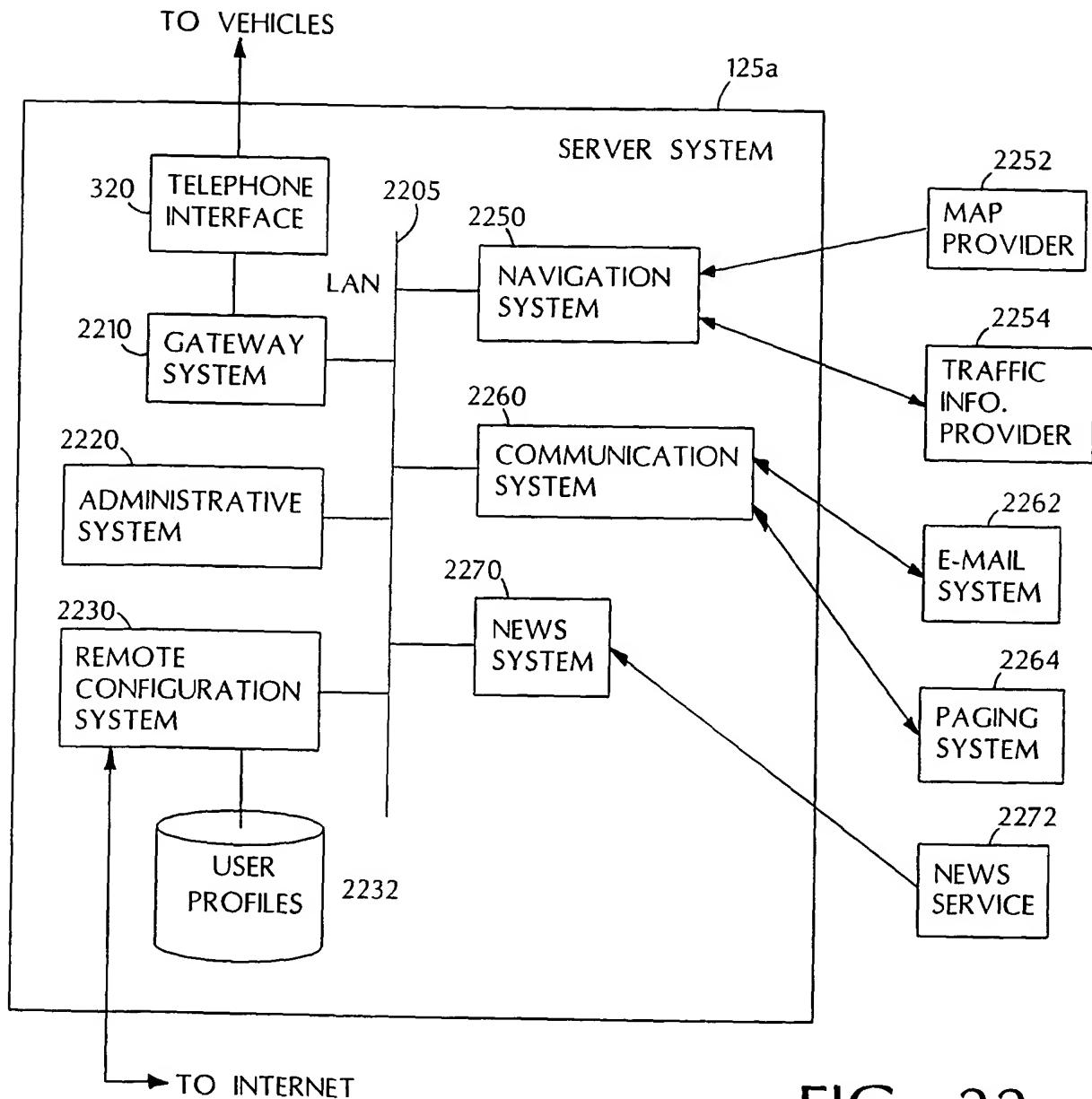


FIG. 22